

Displays for Statistics 5401

Lecture 33

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Class Web Page

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You get canonical variables from the multistandardized $\tilde{\mathbf{x}}^{(1)} = \Sigma_{11}^{-T/2}(\mathbf{x}^{(1)} - \boldsymbol{\mu}^{(1)})$ and $\tilde{\mathbf{x}}^{(2)} = \Sigma_{22}^{-T/2}(\mathbf{x}^{(2)} - \boldsymbol{\mu}^{(2)})$ using left and right singular vectors \mathbf{l}_j and \mathbf{r}_j of

$$\tilde{\boldsymbol{\rho}}_{12} = \text{corr}[\tilde{\mathbf{x}}^{(1)}, \tilde{\mathbf{x}}^{(2)}] = \Sigma_{11}^{-T/2} \Sigma_{12} \Sigma_{22}^{-1/2}.$$

How do you get canonical variables directly from $\mathbf{x}^{(1)}$ and $\mathbf{x}^{(2)}$, rather than from $\tilde{\mathbf{x}}^{(1)}$ and $\tilde{\mathbf{x}}^{(2)}$?

- $z_j^{(1)} = \mathbf{l}_j^T \tilde{\mathbf{x}}^{(1)} = \mathbf{l}_j^T \Sigma_{11}^{-T/2}(\mathbf{x}^{(1)} - \boldsymbol{\mu}^{(1)})$
 $= \mathbf{u}_j^T (\mathbf{x}^{(1)} - \boldsymbol{\mu}^{(1)})$
 $= \mathbf{u}_j^T \mathbf{x}^{(1)} - \mathbf{u}_j^T \boldsymbol{\mu}^{(1)}$, where $\mathbf{u}_j = \Sigma_{11}^{-1/2} \mathbf{l}_j$
- $z_j^{(2)} = \mathbf{r}_j^T \tilde{\mathbf{x}}^{(2)} = \mathbf{r}_j^T \Sigma_{22}^{-T/2}(\mathbf{x}^{(2)} - \boldsymbol{\mu}^{(2)})$
 $= \mathbf{v}_j^T (\mathbf{x}^{(2)} - \boldsymbol{\mu}^{(2)})$
 $= \mathbf{v}_j^T \mathbf{x}^{(2)} - \mathbf{v}_j^T \boldsymbol{\mu}^{(2)}$, where $\mathbf{v}_j = \Sigma_{22}^{-1/2} \mathbf{r}_j$

Thus you need to find \mathbf{u}_j and \mathbf{v}_j . Although they are defined using \mathbf{l}_j and \mathbf{r}_j , they can be computed directly from Σ .

Facts (easily checkable):

$$\Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21} \mathbf{u}_j = \tau_j^2 \Sigma_{11} \mathbf{u}_j = \theta_j \Sigma_{11} \mathbf{u}_j$$

$$\Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12} \mathbf{v}_j = \tau_j^2 \Sigma_{22} \mathbf{v}_j = \theta_j \Sigma_{22} \mathbf{v}_j$$

- Coefficient vector \mathbf{u}_j for $z_j^{(1)}$ is a eigenvector of $\Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}$ relative to Σ_{11}
- Coefficient vector \mathbf{v}_j for $z_j^{(2)}$ is a eigenvector of $\Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12}$ relative to Σ_{22}

So you can find canonical variables by solving two relative eigenvalue/vector problems involving pieces of Σ .

Usually, the canonical variables are defined as

$$z_j^{(1)} = \mathbf{u}_j^T \mathbf{x}^{(1)} = (\Sigma_{11}^{-1/2} \boldsymbol{\ell}_j)^T \mathbf{x}^{(1)}$$

$$z_j^{(2)} = \mathbf{v}_j^T \mathbf{x}^{(1)} = (\Sigma_{22}^{-1/2} \mathbf{r}_j)^T \mathbf{x}^{(2)}$$

without subtracting means. These differ only by constants $\mathbf{u}_j^T \boldsymbol{\mu}^{(1)}$ and $\mathbf{v}_j^T \boldsymbol{\mu}^{(1)}$ from the previous definition, and

$$\mathbf{u}_j^T \boldsymbol{\mu}^{(1)} = E[z_j^{(1)}], \quad \mathbf{v}_j^T \boldsymbol{\mu}^{(1)} = E[z_j^{(2)}]$$

My examples have not, of course, had to do with population principal components, but rather with sample canonical correlations.

You define

- *sample* canonical correlations $\hat{\tau}_j$
- pairs of sample canonical variables $\hat{z}_j^{(1)}$ and $\hat{z}_j^{(2)}$

in a similar way, starting with \mathbf{S} instead of Σ .

Continue with analysis of artificial data:

```
Cmd> s <- tabs(scores,covar:T)
Cmd> J1 <- run(3); J2 <- run(4,7) # selectors for variables
Cmd> s11 <- s[J1,J1]; s22 <- s[J2,J2]
Cmd> s12 <- s[J1,J2]; s21 <- s12'
Cmd> tauhatsq <- releigenvals(s21 %**% solve(s11) %**% s12, s22)
Cmd> tauhatsq # squared canonical correlations
(1) 0.83093 0.030001 0.0089408 6.5688e-18
```

Compute canonical correlations $\hat{\tau}_j$ from SVD of correlation matrix of multi-standardized data:

```
Cmd> tauhat <- svd(cor(scores[,J1] %**% solve(cholesky(s11)),\
  scores[,J2] %**% solve(cholesky(s22)))[J1,J2])
Cmd> tauhat^2 # same as tauhatsq
(1) 0.83093 0.030001 0.0089408 0
```

There is a close relationship between sample canonical correlations and relative eigenvalues from the regression approach discussed on Monday.

If $\hat{\lambda}_j$ are the sample eigenvalues of H relative to E in either the multivariate regression of $\mathbf{x}^{(1)}$ on $\mathbf{x}^{(2)}$ or of $\mathbf{x}^{(2)}$ on $\mathbf{x}^{(1)}$, then

$$\hat{\tau}_i = \sqrt{\hat{\theta}_i} = \sqrt{\{\hat{\lambda}_i / (1 + \hat{\lambda}_i)\}}$$

```
Cmd> manova("x2 = x1_1 + x1_2 + x1_3",silent:T)
Cmd> h2 <- sum(SS[run(2,4),,]); e2 <- SS[5,,]
Cmd> lambdahat <- releigenvals(h2,e2)
Cmd> lambdahat
(1) 4.9149 0.030929 0.0090215 1.2698e-15
Cmd> lambdahat[run(3)]/(1 + lambdahat[run(3)])
(1) 0.83093 0.030001 0.0089408 thetahat = tauhat^2
Cmd> tauhatsq[run(3)]
(1) 0.83093 0.030001 0.0089408
```

The correlation canonical variables $\hat{z}_j^{(1)}$ and $\hat{z}_j^{(2)}$ are the same as the MANOVA canonical variables of regressions of $\mathbf{x}^{(1)}$ on $\mathbf{x}^{(2)}$ and of $\mathbf{x}^{(2)}$ on $\mathbf{x}^{(1)}$, except possibly for change of sign.

Alternative Approach: Find features or summaries of $\mathbf{x}^{(1)}$ and $\mathbf{x}^{(2)}$ that are highly correlated with each other.

This is the more traditional approach to canonical correlation.

We concentrate on linear features $\mathbf{u}^T \mathbf{x}^{(1)}$ and $\mathbf{v}^T \mathbf{x}^{(2)}$ and try to find \mathbf{u} and \mathbf{v} to maximize (make as large as possible)

$$\begin{aligned} \rho^2[\mathbf{u}^T \mathbf{x}^{(1)}, \mathbf{v}^T \mathbf{x}^{(2)}] &= \frac{\text{Cov}[\mathbf{u}^T \mathbf{x}^{(1)}, \mathbf{v}^T \mathbf{x}^{(2)}]^2}{\text{V}[\mathbf{u}^T \mathbf{x}^{(1)}] \text{V}[\mathbf{v}^T \mathbf{x}^{(2)}]} \\ &= \frac{(\mathbf{u}^T \Sigma_{12} \mathbf{v})^2}{(\mathbf{u}^T \Sigma_{11} \mathbf{u})(\mathbf{v}^T \Sigma_{22} \mathbf{v})} \end{aligned}$$

We work with ρ^2 because the sign of the correlation will be arbitrary.

I'll skip any derivation, but the solution can be stated using relative eigenvectors:

- $\mathbf{u} = \mathbf{u}_1$, where $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_p$ are the **relative eigenvectors** of

$$\Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21} \text{ relative to } \Sigma_{11} \text{ (both } p \times p \text{),}$$

with corresponding *relative eigenvalues* $\theta_1 \geq \theta_2 \geq \dots \geq \theta_p$.

- $\mathbf{v} = \mathbf{v}_1$, where $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ are the **relative eigenvectors** of

$$\Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12} \text{ relative to } \Sigma_{22} \text{ (both } q \times q \text{),}$$

with corresponding *relative eigenvalues* $\theta_1 \geq \theta_2 \geq \dots \geq \theta_q$.

Furthermore the maximized value (largest squared correlation) is $\theta_1 = \tau_1^2$.

These are the same coefficient vectors from the first approach to canonical correlation.

That is

$$\max_{\mathbf{u}, \mathbf{v}} \rho^2[\mathbf{u}^T \mathbf{x}^{(1)}, \mathbf{v}^T \mathbf{x}^{(2)}] = \rho^2[\mathbf{u}_1^T \mathbf{x}^{(1)}, \mathbf{v}_1^T \mathbf{x}^{(2)}] = \theta_1$$

Note: These θ_j 's are the same as before, that is $\theta_j = \tau_j^2$ where τ_j is a SV of $\tilde{\Sigma}_{12}$.

With the usual normalization for \mathbf{u}_1 ,

$$V[\mathbf{u}_1^T \mathbf{x}^{(1)}] = \mathbf{u}_1^T \Sigma_{11} \mathbf{u}_1 = 1$$

and

$$V[\mathbf{v}_1^T \mathbf{x}^{(2)}] = \mathbf{v}_1^T \Sigma_{22} \mathbf{v}_1 = 1.$$

and

$$\text{Cov}[\mathbf{u}_1^T \mathbf{x}^{(1)}, \mathbf{v}_1^T \mathbf{x}^{(2)}] = \tau_1 = \sqrt{\theta_1}.$$

Similarly

$$\begin{aligned} z_j^{(1)} &= \mathbf{u}_j^T \mathbf{x}^{(1)}, & j &= 1, \dots, \min(p, q) \\ z_j^{(2)} &= \mathbf{v}_j^T \mathbf{x}^{(2)} \end{aligned}$$

have $\text{Corr}[z_j^{(1)}, z_j^{(2)}] = \tau_j = \sqrt{\theta_j}$.

$z_j^{(1)}$ and $z_j^{(2)}$ have the largest squared correlation of any linear combinations uncorrelated with $z_k^{(1)}$ and $z_k^{(2)}$, $k < j$

Here is what the correlation matrix (and variance matrix) of standardized canonical variables looks like when $p = 4$ and $q = 3$.

$$V[\mathbf{z}] = \begin{bmatrix} 1 & 0 & 0 & \sqrt{\theta_1} & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & \sqrt{\theta_2} & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & \sqrt{\theta_3} & 0 \\ \hline \sqrt{\theta_1} & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & \sqrt{\theta_2} & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & \sqrt{\theta_3} & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{z} = [z_1^{(1)}, z_2^{(1)}, z_3^{(1)}, z_1^{(2)}, z_2^{(2)}, z_3^{(2)}, z_4^{(2)}]^T$$

There are only $s = \min(3, 4) = 3$ non-zero canonical correlations $\tau_1 = \sqrt{\theta_1}$, $\tau_2 = \sqrt{\theta_2}$ and $\tau_3 = \sqrt{\theta_3}$. Note that all correlations with $z_4^{(2)}$ are 0.

In general, there are $s = \min(p,q)$ pairs $(z_j^{(1)}, z_j^{(2)})$ of canonical variables.

All the correlation between $\mathbf{x}^{(1)}$ and $\mathbf{x}^{(2)}$ is "concentrated" in

$$\tau_i = \text{corr}[z_i^{(1)}, z_i^{(2)}], i = 1, \dots, s.$$

When $p \neq q$, there are $|p - q|$ additional unpaired canonical variables that not correlated with anything and have no significance.

You define *sample* canonical correlations and correlation canonical variables the same way using the sample eigenvalues $\hat{\theta}_i = \hat{\tau}_i^2$ and eigenvectors $\hat{\mathbf{u}}_i$ and $\hat{\mathbf{v}}_i$ of

- $\mathbf{S}_{12} \mathbf{S}_{22}^{-1} \mathbf{S}_{21}$ relative to \mathbf{S}_{11}
- $\mathbf{S}_{21} \mathbf{S}_{11}^{-1} \mathbf{S}_{12}$ relative to \mathbf{S}_{22} .

```

Cmd> eigs21 <- releigen(s12 %*% solve(s22) %*% s21, s11)
Cmd> eigs12 <- releigen(s21 %*% solve(s11) %*% s12, s22)
Cmd> uhat <- eigs21$vectors; vhat <- eigs12$vectors

Cmd> list(uhat,vhat)
uhat      REAL      3      3
vhat      REAL      4      4

Cmd> sqrt(eigs21$values) # canonical correlations
(1)  0.91156  0.17321  0.094556

Cmd> sqrt(eigs12$values[run(3)]) # canonical correlations
(1)  0.91156  0.17321  0.094556

Cmd> Z1 <- x1 %*% uhat; Z2 <- x2 %*% vhat
    
```

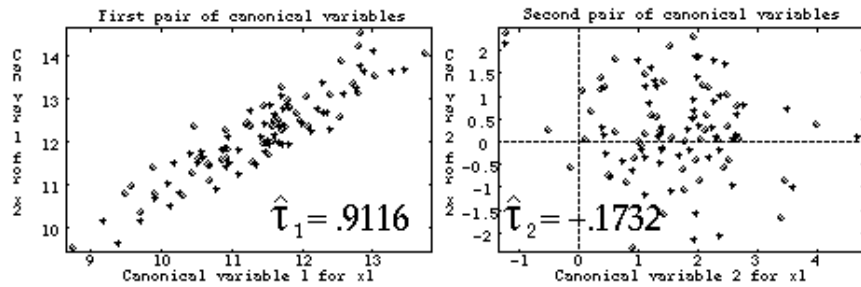
Z1 and Z2 contain canonical variables computed using relative eigenvectors.

```

Cmd> print(format:"7.4f",cor(Z1,Z2))
MATRIX:
(1,1)  1.0000 -0.0000 -0.0000:  0.9116  0.0000 -0.0000  0.0000
(2,1) -0.0000  1.0000 -0.0000: -0.0000 -0.1732 -0.0000 -0.0000
(3,1) -0.0000 -0.0000  1.0000:  0.0000  0.0000  0.0946 -0.0000
(4,1)  0.9116 -0.0000  0.0000:  1.0000  0.0000  0.0000 -0.0000
(5,1)  0.0000 -0.1732  0.0000:  0.0000  1.0000 -0.0000 -0.0000
(6,1) -0.0000 -0.0000  0.0946:  0.0000 -0.0000  1.0000  0.0000
(7,1)  0.0000 -0.0000 -0.0000: -0.0000 -0.0000  0.0000  1.0000
    
```

What do you do with canonical variables?
 One thing to do is to make scatter plots of $\hat{z}_j^{(2)}$ vs $\hat{z}_j^{(1)}$.

```
Cmd> plot(Z1[,1],Z2[,1],xlab:"Canonical variable 1 for x1",\
         ylab:"Can var 1 for x2",\
         title:"First pair of canonical variables")
Cmd> plot(Z1[,2],Z2[,2],xlab:"Canonical variable 2 for x1",\
         ylab:"Can var 2 for x2",\
         title:"Second pair of canonical variables")
```



These are plots of $\hat{z}_1^{(2)}$ vs $\hat{z}_1^{(1)}$ (left) and $\hat{z}_2^{(2)}$ vs $\hat{z}_2^{(1)}$ (right).

And you can look at \hat{u}_j and \hat{v}_j to gain insight on what the canonical variables are made up from, much as you can do in MANOVA.

The $\hat{\theta}_i$ have the same information as the eigenvalues $\hat{\lambda}_1, \hat{\lambda}_2, \dots$ of \mathbf{H} relative to \mathbf{E} that appear in the multivariate regression tests of $\boldsymbol{\rho}_{12} = \mathbf{0}$.

$\hat{\theta}_i = \hat{\lambda}_i / (1 + \hat{\lambda}_i)$	$\hat{\lambda}_i = \hat{\theta}_i / (1 - \hat{\theta}_i)$
--	---

Only $s = \min(p,q)$ of these are non-zero. The regression hypothesis and error matrices are

$$\mathbf{H}_{1.2} = \mathbf{f}_e \mathbf{S}_{12} \mathbf{S}_{22}^{-1} \mathbf{S}_{21}, \quad \mathbf{E}_{1.2} = \mathbf{f}_e \mathbf{S}_{11} - \mathbf{H}_{1.2}, \quad \mathbf{x}^{(1)} \text{ on } \mathbf{x}^{(2)}$$

$$\mathbf{H}_{2.1} = \mathbf{f}_e \mathbf{S}_{21} \mathbf{S}_{11}^{-1} \mathbf{S}_{12}, \quad \mathbf{E}_{2.1} = \mathbf{f}_e \mathbf{S}_{22} - \mathbf{H}_{2.1}, \quad \mathbf{x}^{(2)} \text{ on } \mathbf{x}^{(1)}$$

So $\hat{\lambda}_i$ is the i^{th} eigenvalue of $\mathbf{H}_{1.2}$ relative to $\mathbf{E}_{1.2}$ or of $\mathbf{H}_{2.1}$ relative to $\mathbf{E}_{2.1}$

When $H_0: \boldsymbol{\rho}_{12} = \mathbf{0}$ is true,

$$\{\hat{\lambda}_i\} = \{\hat{\theta}_i / (1 - \hat{\theta}_i)\}$$

You can use any of the MANOVA tests based on relative eigenvalues.

In terms of the canonical correlations

and the matrix $\mathbf{S}_{11}^{-1}\mathbf{S}_{12}\mathbf{S}_{22}^{-1}\mathbf{S}_{21}$

Hotelling's trace

$$\begin{aligned} \sum \hat{\lambda}_i &= \sum \hat{\theta}_i / (1 - \hat{\theta}_i) \\ &= \text{tr}(\mathbf{E}_{1,2}^{-1}\mathbf{H}_{1,2}) \\ &= \text{tr}((\mathbf{S}_{11} - \mathbf{S}_{12}\mathbf{S}_{22}^{-1}\mathbf{S}_{21})^{-1}\mathbf{S}_{12}\mathbf{S}_{22}^{-1}\mathbf{S}_{21}) \\ &= \text{tr}((\mathbf{I}_p - \mathbf{S}_{11}^{-1}\mathbf{S}_{12}\mathbf{S}_{22}^{-1}\mathbf{S}_{21})^{-1}\mathbf{S}_{11}^{-1}\mathbf{S}_{12}\mathbf{S}_{22}^{-1}\mathbf{S}_{21}) \end{aligned}$$

LR test

$$\begin{aligned} 1/\Pi(1 + \hat{\lambda}_i) &= \Pi(1 - \hat{\theta}_i) \\ &= \det(\mathbf{E}_{1,2}) / \det(\mathbf{H}_{1,2} + \mathbf{E}_{1,2}) \\ &= \det(\mathbf{I}_p - \mathbf{S}_{11}^{-1}\mathbf{S}_{12}\mathbf{S}_{22}^{-1}\mathbf{S}_{21}) \end{aligned}$$

Pillai's trace

$$\begin{aligned} \sum \hat{\lambda}_i / (1 + \hat{\lambda}_i) &= \sum \hat{\theta}_i \\ &= \text{tr}\{(\mathbf{H}_{1,2} + \mathbf{E}_{1,2})^{-1}\mathbf{H}_{1,2}\} \\ &= \text{tr}(\mathbf{S}_{11}^{-1}\mathbf{S}_{12}\mathbf{S}_{22}^{-1}\mathbf{S}_{21}) \end{aligned}$$

In these equations you can replace \mathbf{S}_{11} by \mathbf{S}_{22} and $\mathbf{S}_{11}^{-1}\mathbf{S}_{12}\mathbf{S}_{22}^{-1}\mathbf{S}_{21}$ by $\mathbf{S}_{22}^{-1}\mathbf{S}_{21}\mathbf{S}_{11}^{-1}\mathbf{S}_{12}$

Beyond Canonical Correlations

Here are two paths you might follow.

1. Use quadratic features instead of linear features. That is, try to find vectors \mathbf{u} and \mathbf{v} and symmetric matrices \mathbf{A} and \mathbf{B} such that

$$\text{Corr}[\mathbf{u}'\mathbf{x}^{(1)} + \mathbf{x}^{(1)'}\mathbf{A}\mathbf{x}^{(1)}, \mathbf{v}'\mathbf{x}^{(2)} + \mathbf{x}^{(2)'}\mathbf{B}\mathbf{x}^{(2)}]$$

is as large as possible

2. Describe the pattern of correlation among $k > 2$ sets of variables $\mathbf{x}^{(1)}, \mathbf{x}^{(2)}, \dots, \mathbf{x}^{(k)}$. One possibility would be to find vectors $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$ that minimize $\det(\mathbf{R}_U)$, where \mathbf{R}_U is the correlation matrix of $\mathbf{u}_1'\mathbf{x}^{(1)}, \mathbf{u}_2'\mathbf{x}^{(2)}, \dots, \mathbf{u}_k'\mathbf{x}^{(k)}$.

Since $\det(\mathbf{R}_U) = 1 - \rho^2[\mathbf{u}_1'\mathbf{x}^{(1)}, \mathbf{u}_2'\mathbf{x}^{(2)}]$ when $k = 2$, this leads to the ordinary canonical correlations when there are $k = 2$ groups of variables..

The classification problem

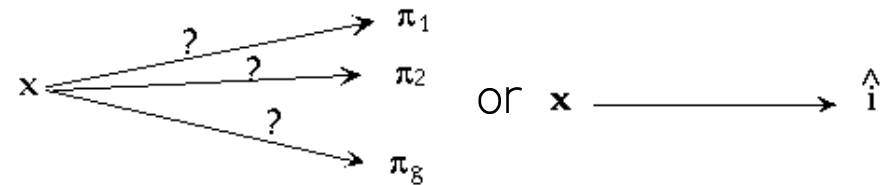
Situation: You have data \mathbf{x} (1 or several variables) on an individual that is known to belong to one of g distinct populations $\pi_1, \pi_2, \dots, \pi_g$.

The **classification problem**: Find a "rule" or formula which uses \mathbf{x} to "guess" or "estimate" the population π_j the individual belongs to.

Example: When each population consists of patients with a particular disease and \mathbf{x} contains an individual's medical history and test results, the classification problem would be to diagnose the correct disease from the information in \mathbf{x} .

More formally, suppose

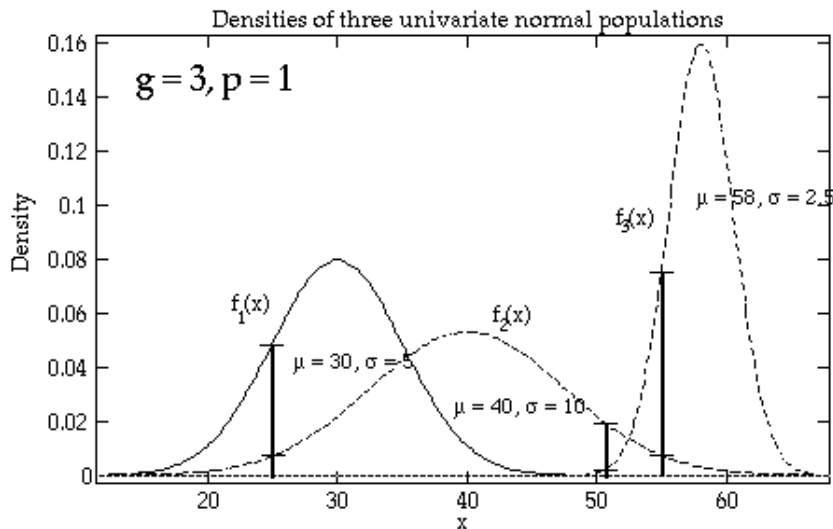
- You have a random vector \mathbf{x} (the data) of p characteristics (variables).
- You know \mathbf{x} has one of g densities $f_1(\mathbf{x}), f_2(\mathbf{x}), \dots, f_g(\mathbf{x})$, where $f_j(\mathbf{x})$ defines the distribution of \mathbf{x} in population π_j .
- You seek a procedure or formula (a "rule") that maps \mathbf{x} to a population.



Here \hat{i} is the guessed index of the population chosen.

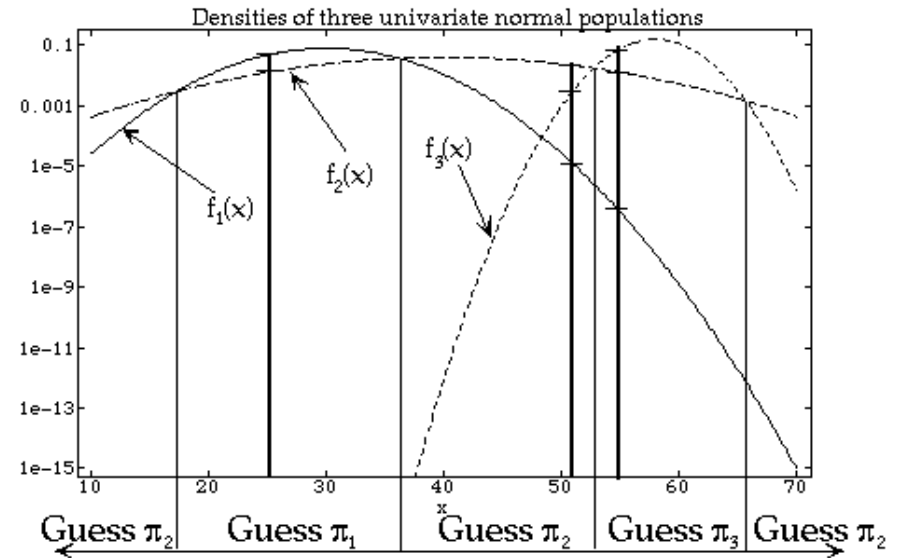
Suppose the observed \mathbf{x} is much less likely to be observed in population π_1 (density $f_1(\mathbf{x})$) than in population π_2 (density $f_2(\mathbf{x})$). Then you might reasonably guess π_2 in preference to π_1 .

Here are densities for three $p=1$ populations with normal distributions.



When $x = 25$, you would choose π_1 over π_2 or π_3 ; when $x = 51$, you would choose π_2 ; when $x = 55$, you would choose π_3 .

It's often easier to compare densities when they are plotted in a log scale.

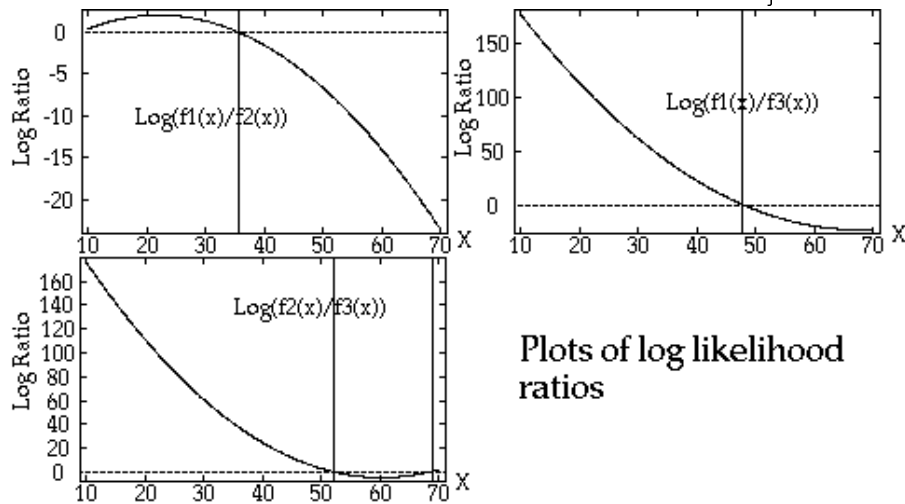


The extra vertical lines are where the densities intersect.

Under the graph is a sensible rule for picking one of these three populations - pick the population with largest density.

Near the boundary points you wouldn't be very sure about your decision based on this rule.

The logs of the ratios $f_j(x)/f_k(x)$ are informative for deciding between π_j and π_k .



The 0 line is the line of equal likelihood. These let you choose between π_j and π_k

- When $10 < x < 35$, you would probably assign x to π_1 (above 0 in top 2 plots)
- x near 45 you would assign x to π_2
- $60 < x < 70$ you would assign x to π_3 .

It looks like for $x < 10$ and $x > 70$, you should prefer π_2 to π_1 and π_3 even though x is nearer to μ_1 or μ_3 than to μ_2 .

Effect of rarity

Suppose you knew, for example, that seeing *any* observation, regardless of value, from π_2 was extremely *rare* as compared to either π_1 or π_3 . Then this "obvious" way to guess a population might change.

In that case, you might classify a value of $x = 45$ as coming from π_1 , even though it would be an unlikely value to see from π_1 , just because it is unlikely to see *any* individual from π_2 .

In the extreme, if the chance of seeing any individual from π_2 was $1/1,000,000$, for all practical purposes you can probably exclude π_2 from consideration and never pick π_2 .